Program			Type of studies (cycle)		Third cycle							
			Name of the program		SEE Doctoral Studies in Mathematical Sciences							
Course												
Course title Contin			ous Dynamical Systems									
Course code		Semester		Course status		ECTS credits	Contact hours					
I		II				10	30					
Teaching staff	Teacher			Prof. Dr. Mustafa Kulenović								
	Other staff			Prof. Dr. Senada Kalabušić, Prof. Dr. Ognyan Christov								
Course goals	The goal of the course is to give to the students a basic knowledge about dynamical systems and a											
	qualitative insight to differential equations.											
Course content/topics												

Review of basic concepts and theorems in ODE. Vector fields, flows, linear systems,

fixed points, linearization, phase portraits, stability

Floquet theorem, logarithm of the matrix

Poincare maps. Examples. Duffing equation

Equivalence, equivalence of linear systems. Hartman - Grobman's theorem.

Limit sets. Poincare – Bendixson theorem.

Normal forms. Resonances. Poincare theorem.

Center manifolds. Approximate computations.

Bifurcation of fixed points. A zero eigenvalue. Hopf bifurcation.

Attractors. Lorenz, Rosler and Chua attractors.

LITERATURE					Grading					
		differential equati	ions",		Criterion	Points	Cut-off			
various edit	ions.					points				
		, J.A. Yorke, Chaos	1.	Homework assignment	20	10				
	•	Systems), Springer, 19	2.	Project	30	15				
		es, Nonlinear Oscilla	3	Final exam	50	30				
•	Systems, and Bif			Total	100	55				
	ields, Springer, 1									
		ns with applications								
	a, BirkhÄauser,									
	Systems, Springe	fferential Equations								
•		Devaney, Differ								
		ns and an introduction								
chaos, Else		no and an introduction								
		Introduction to Ch								
	Systems, 2nd edi									
•	•	rete Chaos, Chap								
Hall/CRC,		, 1								
[9] M.R.S. Ku	enovi´c, O. Me	rino, Discrete Dyna	ımical							
Systems and	l Difference Eq	uations with Mathem	natica,							
Chapman-I	Iall/CRC, 2002.									
[10] C. Robinson, Dynamical Systems, CRC, 2nd edition,										
1999.										
[11] S. Wiggins, Introduction to applied nonlinear										
dynamical s	ystems and chac	s, Springer, 2003.								